Department of Mechanical Engineering

PROJECT PROPOSAL

1	Title of the project: **Design, Simulation, and Implementation of Robot motion** Area of project: Kinematic analysis of Robot motion
2	Abstract: Robot motion is simulated using inverse kinematics to develop a motion sequence for application. A mode will be developed to produce a sequence and build a model.
3	Expected Outcome of the project: Realization of simulated model
4	Number of interns required - 4
5	Project guide – Dr Pradip P Patil
6	Preferred year of the intern - TE / BE
7	Duration of the project – 6 months

Dr. Pradip P. Patil   Prof Dr. Rupendra Nehete
Internship Coordinator   (HOD-ME)

SIES Graduate School of Technology, Nerul, Navi Mumbai